

SIL2 / PLd Certified sensor

QG65N-KIXv-360-CANS-C(F)M-2d

Safety inclination sensor

1 axis vertical mounting

Programmable device
Interface: CANopen Safety

SIL CL 2 (acc. to IEC 62061)
PLd (acc. to EN ISO 13849)

Measuring range
360°



CANopen
safety easy to use



General specifications 12082/12077, v20180117

Reinforced plastic injection molded (Faradex DS, black, EMI shielded by stainless steel fiber in PC)

60x50x27 mm

4x M5x25 mm zinc plated pozidrive screws included (optional: 2x Ø4mm positioning pins)

IP67

0 - 100%

approx. 110 gram

8 - 60 V dc SELV

Yes

≤ 75 mA

-40 .. +85 °C

-40 .. +85 °C

360°

Yes (CANout 0 = 0°), range: 360°

0 - 20 Hz

overall 0,1° typ.

< ± 0,05° typ. after centering

< ± 0,1° typ. (< ± 0,15° max.)

not applicable

0,01°

± 0,01°/K typ.

10.000 g

According to ISO 11898-1 & ISO 11898-2 (also known as CAN 2.0 A/B)

CANopen Safety protocol: EN 50325-5, CANopen protocol: EN 50325-4 (CiA 301 v4.0 & 4.2.0)

CANopen device profile for inclinometers: CiA 410 version 2.0.0

125 kbit/s (default, range 10/20/50/100/125/250/500/800/1000 kbit/s)

01h (default, range: 01h - 3Fh) (01h - 7Fh with adapted COB-ID's)

50 ms (default, range 10-500 ms)

off (default, range on/off)

Integer: -17999 to 18000 (SRDO:byte2, 1) (byte 3,4,5,6,7,8: integer 0)

FFh + 2x node ID (for Node ID=01h: SRDO1 COB-ID1=101h)

100h + 2x node ID (for Node ID=01h: SRDO1 COB-ID2=102h)

80ms in CAN object dictionary, worst case 100ms

20ms

Output filter disabled

Emergency message 080h+Node-ID followed by NMT stop state (no CAN communication)

< 1 s

by CANopen object dictionary (CAN parameters, filtering)

Housing

Dimensions (indicative)

Mounting

Ingress Protection (IEC 60529)

Relative humidity

Weight

Supply voltage

Polarity protection

Current consumption

Operating temperature

Storage temperature

Measuring range

Centering function

Frequency response (-3dB)

Accuracy (typ. and/or 2σ)

Offset error

Non linearity

Sensitivity error

Resolution

Temperature coefficient

Max mechanical shock

CAN interface (hardware)

CANopen application layer and communication profile

Baud rate

Node Id

TPDO1 event time

Sync mode (TPDO's), Heartbeat

Output format

SRDO1 COB-ID1

SRDO1 COB-ID2

Safeguard cycle time (SCT)

Safety related validation time (SRVT)

Filtering

Reaction on error

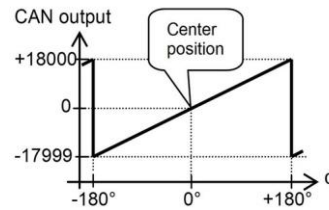
Boot time

Programming options

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CANoutput = $100 \cdot \alpha$

Transfer characteristic

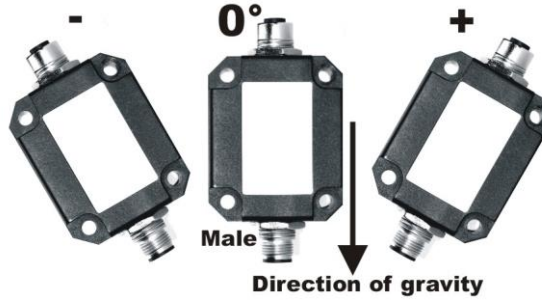


Rotation in vertical plane.

Lateral tilt sensitivity error:
 $< \pm 0,03^\circ$ lateral tilt (typ.)
 Max. lateral tilt: 45°

Drawn in the default 0° position.

Measurement orientation



Connection

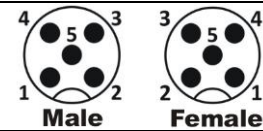
Connectivity (length $\pm 10\%$)

Male only or Male & Female (internal T-junction) M12 connector (5 pins, A-coding)

(CiA303 V1.8.0) (Brass Nickel coated, contacts copper alloy)

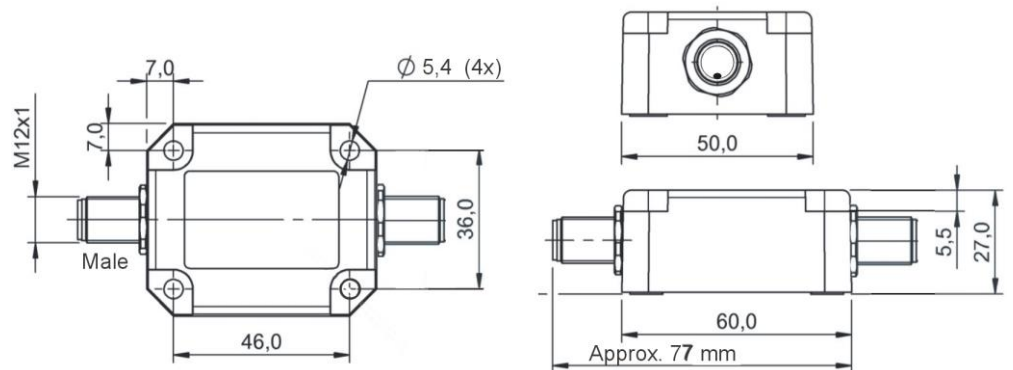
No bus termination inside. A CANbus always has to be terminated properly. For bus termination order separate M12 termination resistor (optional: T-connector)

- Pin 1: Shield
- Pin 2: Vcc
- Pin 3: Gnd & CAN_GND
- Pin 4: CAN_H
- Pin 5: CAN_L



Wire / pin coding

Mechanical dimensions (indicative only)



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CAN-manual, EDS-file, Safety information, Ordering codes

A CANopen-safety manual, EDS-files (CiA306 V1.3.0) and a Declaration of Conformity are available on www.dis-sensors.com/downloads

Safety information:

- this datasheet + relevant manual must be read and understood before using this safety device
- certified level: SIL CL 2 (acc. to IEC 62061), PLd (acc. to EN ISO 13849)
- EC type examination by DEKRA EXAM GmbH Reg. no.: ZP/C015/16
- hardware architecture: HFT=0 (according IEC 62061, CAT.2 (according to EN ISO 13849)
- Standard (-40°C to +45°C): MTTFd: 447 year, DC: 93%, CCF: 70 pt, SFF: 98%, PFHd: 14E-09
- High Temp. (up to +85 °C): MTTFd: 73 year, DC: 93%, CCF: 70 pt, SFF: 98%, PFHd: 91E-09
- only a SELV power supply should be used
- Redundancy Compare Time (error if this time is expired): customer adjustable (default 2000ms)
- Redundancy Compare Angle (error if angle-difference > this value): customer adjustable (default 3°)
- Redundancy error: Redundancy Compare Angle & Redundancy Compare Time exceeded
- Error: any detected error or a redundancy error
- Safety Related Fault Respons Time (SRFRT): 100ms + Redundancy Compare Time (default 2000ms)

As this device is accelerometer-based the sensor is inherent sensitive for accelerations/vibrations. Application specific testing must be carried out to check whether this sensor will fulfil your requirements.

Ordering codes:

M12 Male: QG65N-KIXv-360-CANS-CM-2d, 12082

M12 Male & Female: QG65N-KIXv-360-CANS-CFM-2d, 12077